Modular 2/4-Channel PID Temperature **Controllers with Screwless Connector**

TM Series

INSTRUCTION MANUAL

TCD220001AE

Autonics

Thank you for choosing our Autonics product.

Read and understand the instruction manual and manual thoroughly before using the product.

For your safety, read and follow the below safety considerations before using. For your safety, read and follow the considerations written in the instruction manual, other manuals and Autonics website

Keep this instruction manual in a place where you can find easily.

The specifications, dimensions, etc are subject to change without notice for product improvement Some models may be discontinued without notice.

Follow Autonics website for the latest information.

Safety Considerations

- Observe all 'Safety Considerations' for safe and proper operation to avoid hazards. • ▲ symbol indicates caution due to special circumstances in which hazards may occur.

Warning Failure to follow instructions may result in serious injury or death

- 01. Fail-safe device must be installed when using the unit with machinery that may cause serious injury or substantial economic loss. (e.g. nuclear power control, medical equipment, ships, vehicles, railways, aircraft, combustion apparatus, safety equipment, crime/disaster prevention devices, etc.) ailure to follow this instruction may result in personal injury, economic loss or fire.
- 02. Do not use or store the unit in the place where flammable/explosive/ corrosive gas, high humidity, direct sunlight, radiant heat, vibration, impact or salinity may be present.
- ow this instruction may result in explosion or fire.
- 03. Install the device in panel to use. Failure to follow this instruction may result in fire.
- 04. Do not connect, repair, or inspect the unit while connected to a power
- source.
- Failure to follow this instruction may result in fire. 05. Check 'Connections' before wiring.
- ailure to follow this instruction may result in fire.
- 06. Do not disassemble or modify the unit. Failure to follow this instruction may result in fire.

↑ Caution Failure to follow instructions may result in injury or product damage

01. When connecting the power input and relay output, use AWG 26 to 12 cable and connecting the sensor input and communication cable without dedicated cable, use AWG 28 to 14 cable. Failure to follow this instruction may result in fire or malfunction due to contact

- 02. Use the unit within the rated specifications.
- ailure to follow this instruction may result in fire or product damage 03. Use a dry cloth to clean the unit, and do not use water or organic solvent.
- 04. Keep the product away from metal chip, dust, and wire residue which flow into the unit.

Failure to follow this instruction may result in fire or product damage.

Cautions during Use

- Follow instructions in 'Cautions during Use'. Otherwise, it may cause unexpected
- Check the polarity of the terminals before wiring the temperature sensor. For RTD temperature sensor, wire it as 3-wire type, using cables in same thickness and
- For thermocouple (CT) temperature sensor, use the designated compensation wire for extending wire.
- Keep away from high voltage lines or power lines to prevent inductive noise. In case of installing power line and input signal line closely, use line filter or varistor at power line and shielded wire at input signal line.
- Do not use near the equipment which generates strong magnetic force or high
- Do not apply excessive power when connecting or disconnecting the connectors of the product. • Install a power switch or circuit breaker in the easily accessible place for supplying or
- Do not use the unit for other purpose (e.g. voltmeter, ammeter), but temperature
- After changing the input sensor, modify the value of the corresponding parameter.
- When changing the input sensor, turn off the power first before changing.

- 24 VDC == model power supply should be insulated and limited voltage/current or Class 2, SELV power supply device.
- Do not overlapping communication line and power line.
- Use twisted pair wire for communication line and connect ferrite bead at each end of line to reduce the effect of external noise.
- Make a required space around the unit for radiation of heat.
- For accurate temperature measurement, warm up the unit over 20 min after turning on the power.
- · Mounting multiple devices in any way other than the specified mounting method may cause heat to build up inside, which will shorten their service life. If there is a possibility of the ambient temperature rising to a temperature above the specified temperature range, take steps, such as installing fans, to cool the device. Be sure that the cooling method in not cooling just the terminal block. If only the terminal block is cooled, measurement errors may occur.
- Make sure that power supply voltage reaches to the rated voltage within 2 sec after supplying power.
- · Do not wire to terminals which are not used.
- Install DIN rail vertically from the ground.
- . This unit may be used in the following environments. Indoors (in the environment condition rated in 'Specifications')
- Altitude Max. 2.000 m
- Pollution degree 2
- Installation category II

Ordering Information

This is only for reference, the actual product does not support all combinations.

FOI Sele	cung the	specified	mode	i, ioilow i	ne Autoni	ics websit	е.	
Т	М	0	-	0	3	4	6	
O Char	nel			6	Control	output		

S: SSR drive

Structure

2: 2 channels

Alarm output

4: Alarm output 1/2/3/4 (2 channels) N. None (4 channels)

Power supply 2.24 VDC

B: Basic module E: Expansion module Since the expansion module is not supplied with

power/comm. terminal. Use it with the basic module.

C: Selectable current or SSR drive output

Product Components

- Product (+ bracket)
- Instruction manual
- Side connector ×1 • Power/Comm. connector ×1 (only for basic module)

Sold Separately

- Current transformer (CT)
- Communication Converter: SCM-US / SCM-38I / SCM-US48I / SCM-WF48

Manual

For proper use of the product, refer to the manuals and be sure to follow the safety considerations in the manuals

Download the manuals from the Autonics website

Software

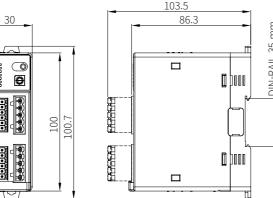
Download the installation file and the manuals from the Autonics website

DAQMaster

DAQMaster is comprehensive device management program. It is available for parameter setting, monitoring.

Dimensions

- Unit: mm, For the detailed drawings, follow the Autonics website.
- · Below is based on basic module



Specifications Power supply Permissible voltage 0 to 110% of rated voltage ≤ 5 W (for Max. load) 50 ms (2 channels synchronous sampling) 100 ms (4 channels synchronous Input specification fer to 'Input Type and Using Range'. CT input T ratio: 1/1.000 surement accuracy: ±5% F.S. ±1 digit ON: ≤ 1 kΩ, OFF: ≥ 100 kΩ residual voltage: ≤ 1.5 VDC= leakage current: ≤ 0.1 mA utflow current: ≈ 0.5 mA per input 50 VAC~ 3 A 1a, 30 VDC= 3 A 1a 22 VDC= ±3 V. ≤ 30 mA $12 \text{ VDC} = \pm 3 \text{ V.} \le 30 \text{ mA}$ output DC 4 - 20 mA or DC 0 - 20 mA Current Alarm output 250 VAC~ 3 A 1a RS485 Comm. Modbus ASCII / RTL Display type Ione- parameter setting and monitoring is available at external devices ON/OFF, P, PI, PD, PID Control type Proportional band (P) Derivative time (D) Control cycle (T) cycle Electrical Dielectric strength 100,000 operations (250 VAC \sim 3 A load resistance) ween the charging part and the case: 3,000 VAC \sim 50/60 Hz for 1 m de at frequency of 5 to 55 Hz in each X, Y, Z direction for 2 hours $M\Omega$ (500 VDC= megger) W square shaped noise (pulse width 1 µs) by noise simulator o 50 °C, storage: -20 to 60 °C (no freezing or condensation) 85%RH, storage: 35 to 85%RH (no freezing or condensation) Channel insulation ectric strength 1,000 VAC~ Insulation type input part and the power part: 1 kV) Certification CE EX °An " E EHI Basic module: ≈ 174 g (≈ 239 g) • Basic module: ≈ 152 g (≈ 217 g) • Expansion module: ≈ 143 g (≈ 208 g)

Input Type and Using Range

The setting range of some parameters is limited when using the decimal point display

Using range (°C)

Using range (°F)

	K (CA)	1	K (CA) .H	-200	to	1,350	-328	to	2,462
	K (CA)	0.1	K (CA) .L	-200.0	to	1,350.0	-328.0	to	2462.0
	J (IC)	1	J (IC) .H	-200	to	800	-328	to	1,472
	J (IC)	0.1	J (IC) .L	-200.0	to	800.0	-328.0	to	1472.0
	E (CR)	1	E (CR) .H	-200	to	800	-328	to	1,472
	E (CR)	0.1	E (CR) .L	-200.0	to	800.0	-328.0	to	1,472.0
	T (CC)	1	T (CC) .H	-200	to	400	-328	to	752
	I (CC)	0.1	T (CC) .L	-200.0	to	400.0	-328.0	to	752.0
Thermo	B (PR)	1	B (PR)	0	to	1,800	32	to	3,272
-couple	R (PR)	1	R (PR)	0	to	1,750	32	to	3,182
coupie	S (PR)	1	S (PR)	0	to	1,750	32	to	3,182
	N (NN)	1	N (NN)	-200	to	1,300	-328	to	2,372
	C (TT) 01)	1	C (TT)	0	to	2,300	32	to	4,172
	G (TT) 02)	1	G (TT)	0	to	2,300	32	to	4,172
	L (IC)	1	L (IC) .H	-200	to	900	-328	to	1,652
		0.1	L (IC) .L	-200.0	to	900.0	-328.0	to	1,652.0
	U (CC)	1	U (CC) .H	-200	to	400	-328	to	752
		0.1	U (CC) .L	-200.0	to	400.0	-328.0	to	752.0
	Platinel II	1	PLII	0	to	1,400	32	to	2,552
	JPt100 Ω	1	JPt100.H	-200	to	600	-328	to	1,112
	JP1100 12	0.1	JPt100.L	-200.0	to	600.0	-328.0	to	1,112.0
	DPt100 O	1	DPt100.H	-200	to	600	-328	to	1,112
RTD	DF (100 \)	0.1	DPt100.L	-200.0	to	600.0	-328.0	to	1,112.0
KID	DPt50 Ω	0.1	DPt50.L	-200.0	to	600.0	-328.0	to	1,112.0
	Cu50 Ω	0.1	CU 50	-200.0	to	200.0	-328.0	to	392.0
	Cu100 Ω	0.1	CU 100	-200.0	to	200.0	-328.0	to	392.0
	Nickel120 Ω	1	NI12	-80	to	260	-112	to	500

01) C (TT): Same as existing W5 (TT) type sensor 02) G (TT): Same as existing W (TT) type sensor

■ Measurement accuracy

in Measurement accuracy						
Input type	Using temperature	Measurement accuracy				
Thermo -couple	At room temperature (23 ±5 °C)	(PV \pm 0.5% or \pm 1 °C higher one) \pm 1-digit • Thermocouple K, J, T, N, E below -100 °C and L, U, PLII, RTD DPt50 Ω Cu50 Ω : PV \pm 2 °C \pm 1-digit • Thermocouple C, G and R, S below 200 °C: PV \pm 3 °C \pm 1-digit • Thermocouple B below 400 °C: there is no accuracy standards				
RTD	Out of room temperature range	(PV ±0.5% or ±2 °C higher one) ±1-digit •RTD: (PV ±0.5% or ±3 °C higher one) ±1-digit •Thermocouple R, S, B, C, G, L, U: (PV ±0.5% or ±5 °C higher one) ±1-digit •Thermocouple below -100 °C: ±5 °C				

Communication Interface

■ RS485

Protocol	Modbus ASCII / RTU					
Application standard	EIA RS485 compliance with					
Maximum connection	31 units (address: 01 to 31)					
Synchronization type	Asynchronous					
Connection type	Two-wire half duplex					
Comm. effective range	≤ 800 m					
Comm. speed	2,400 / 4,800 / 9,600 (default) / 19,200 / 38,400 / 57,600 / 115,200 bps (parameter)					
Response time	5 to 99 ms (default: 20 ms)					
Start bit	1 bit (fixed)					
Data bit	8 bit (fixed)					
Parity bit	None (default), Odd, Even					
Stop bit	1 bit, 2 bit (default)					
EEPROM life cycle ≈1,000,000 operations (Erase / Write)						
When changing the setting val	ue related to communication interface, reboot the device for normal operation.					

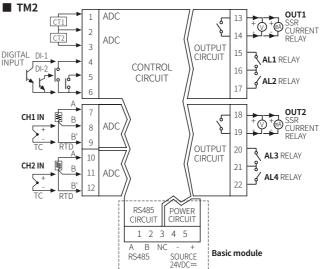
- When changing the setting value related to communication interface, reboot the device for r
 It is not allowed to set overlapping communication address at the same communication line
- It is recommended to use Autonics communication converter. Please use twisted pair wire, which is suitable for RS485 communication.

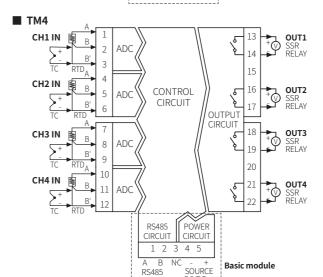
Address

Set the communication address with the communication address setting switch (SW1, default: 1) and communication address group switch (SW2, default: +0).

• WITCH	SCILII	ig as	U, IL U	10631	1010	perat	e con	IIIIIui	iicati	OH.						
SW1																
SW2	0	1	2	3	4	5	6	7	8	9	Α	В	С	D	E	F
+0+16	X	01	02	03	04	05	06	07	08	09	10	11	12	13	14	15
■ +0 +16	16	17	18	19	20	21	22	23	24	25	26	27	28	29	30	31

Connections

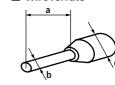




Crimp Terminal Specifications

• Unit: mm, Use the crimp terminal of follow shape.

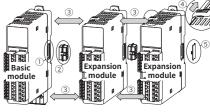
■ Wire ferrule



Terminal number	a	b	с
1 to 12	10	≤ 1.7	≤ 3.7
13 to 22	10	≤ 2.1	≤ 4.2

Installation Method

■ Connection between modules



1. Remove END cover (1) of each module (except END cover of the first and last module). 2. Insert side connector (2) and connect them tightly to

(3) direction (max 30 units) 3. Press lock switch (4) to lock direction.

 Supply adequate power for power input specifications and overall capacity.

(Max. power when connecting 31 modules: 31 units × 5 W=155 W)

■ Mounting with bolts



1. Pull the rail lock at the top and bottom of the module to $\ensuremath{ \mathbb{ 1}}$ direction.

- Separation

2. Insert M4 bolts to $\ensuremath{\textcircled{2}}$ direction and fix it on rail lock. (Tightening torque: 0.5 to 0.9 N m)

■ Mounting on DIN rail

- Installation



1. Hang the top rail lock to DIN rail. 2. Push to ① direction and press to (2)



1. Press the module to ① direction.

. Keep it pressed and pull it to 2 direction

Connector

[Basic module]

Precautions Install the module vertically

• Use end plates (sold separately, not available from Autonics) to fix firmly

Errors

■ Indicator

Name	Status		Description	Troubleshooting
PWR	ON	Red	☐ channel error: Input < Input range, Input > Input range, Input sensor	When the error factor is
СН□	Flash 01)	Red	is open or not connected, Sensor internal communication error	resolved, it automatically returns to normal operation.

01) Cycle: 0.5 sec

■ Communication output, DAQMaster

. ,								
Communication output (decimal)	DAQMaster	Description	Troubleshooting					
'31000'	Display 'OPEN'	Input sensor is open or not connected	When the error factor is					
'30000'	Display 'HHHH' 01)	Input > Input range	resolved, it automatically returns to normal operation.					
'-30000'	Display 'LLLL'01)	Input < Input range	returns to normal operation.					
'31500'	Display '31500'	Sensor internal communication error	Check the power supply (24VDC==). (22)					

01) When HHHH / LLLL error occurs, the control output may occur by recognizing the maximum or minimum input depending on the control type. Please be carefu

02) This error may occur when connecting only the loader port

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